



USING AUXILIARY SENSORS WITHIN TAPESTRY

TAPESTRY is capable of outputting a range of Auxiliary Navigation Sensors used to support and compliment the GPS measurements processed by the User Equipment Under Test.

Auxiliary Sensor Data is comprised of:

• Strapdown Inertial Measurement Unit (IMU).

Using our MFIO expansion card, Tapestry generates Inertial Referenced Delta–Velocity and Delta-Angle for hardware formats such as Honeywell HG-1700, Litton LN200, and some AMRAAM sensors. Both SDLC and Differential RS422 protocol with all hardware handshaking is provided. Data synchronization with the RF output signal is maintained by the Tapestry *Run Scenario* Application.

Automotive Sensor Data

Using our MFIO expansion card, Tapestry constructs and outputs data used by Automotive Navigation Systems. Data consists of Analog 0-5VDC programmable Gyroscopic and Acceleration measurements in a triad package. Odometers and ABS data is provided via a 4-Wheel-Speed-Pulse output. Rate table control, Reverse Signal, and programmable error models are output. Data synchronization with the RF output signal is maintained by the Tapestry *Run Scenario* Application.

- Baro Altimeter. Output via RS232 in a selection of formats and units. Internally this sensor support ICD-INS-059 1553 and related serial output.
- 1553. GPS-INS-059 data output via an optional (COTS-Ballard) 1553 PCI expansion card.
- ARINC-429. In support of aircraft navigation, related message types are output via an optional (COTS-Ballard) ARINC-429 PCI expansion card.
- Serial Data output via RS232 is provided.
- Serial Data output via GPSIP-153
- All data synchronized via 1-PPS to GPS rollovers. Master clock distribution.



